

Building the Opencockpits NAV Radio

With this tutorial I hope to partly address the lack of adequate instruction available for assembly of the Opencockpits radios. This is a shame as the Opencockpits hardware and software offer some of the best value for the home cockpit builder on a budget. There are a number of websites that proved invaluable to my knowledge and understanding of Opencockpits hardware and software and I would highly recommend researching these sites prior to undertaking this build. You'll find a full list at the end of this document.

This tutorial assumes that the user already owns the Opencockpits Mastercard as the associated 7-segment Display cards need to connect to this unit in order to operate. You should also have an understanding of the software SIOC which is used to program the different functions of the radios.



The NAV panel comprises a front plate laser cut and ready for backlighting, backplate, 2 x switch mounting plates and buttons.

In addition you will need the following to complete the NAV radio:

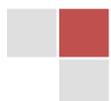
- 2 x OMROM B3F 4050 keyswitches
- 10 x 7-segment display digits
- 1 x CTS288 rotary encoder
- 2 x PCB's for 5 digit display
- 1 x Gray knob
- 1 x Opencockpits Display Card
- Lots of multipin plugs and cables
- Plenty of time and patience
- Coffee, wine, beer or a mix of all

NOTE: The 7-segment displays need to be the Common Cathode variety and all are available from the Opencockpits Shop

Other options you might consider are:

- Dual concentric rotary encoder or alternatively use two rotary encoders to achieve High & Low digit selection (this is what I did).
- 3mm White LED's for backlighting. (Installation details at the end of this document)

The Transfer and Comm Test buttons come in two pieces. Simply glue the black button onto the clear base with superglue. The backing plate is clear to allow light through when backlit.

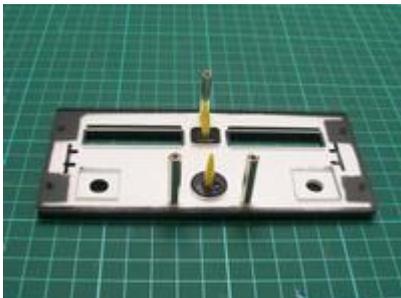


Building the Opencockpits NAV Radio



Here's the result. It will only take a few minutes using superglue. Edges need to be painted black to avoid light leakage when backlit. Use acrylic paint available from any craft shop.

Then some sort of pins need to be installed that will push on the switch mounted above it. I used plastic knitting needles cut to size and glued in place. Be sure to get the length correct. The pointed ends insert into the small hole in the Omron momentary switch for button centering.

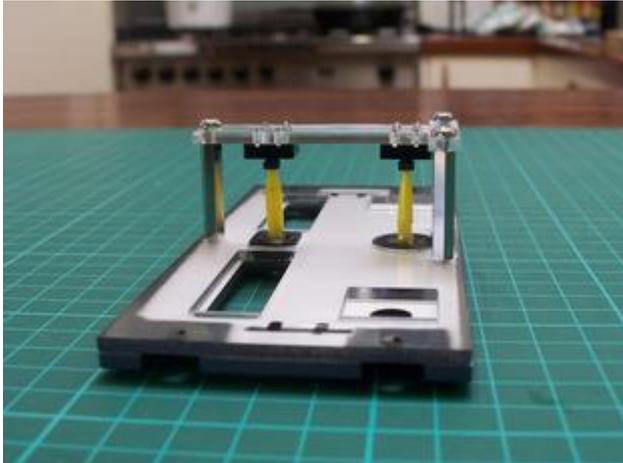


Buttons fit into the backplate and 25mm threaded standoff shafts hold the frontplate to the back and the switches above the buttons as can be seen in the next photo.

These photos show the COMM panel but the principle is the same for all panels.

Glue the Omron switches onto the clear mounting plate and align with the needle ends.





Here you can clearly see how the needle ends insert into the switches and stop them flailing about.

Encoders come with long shafts that need to be cutdown. Measure the required length which will depend on your choice of knob.

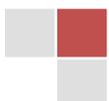


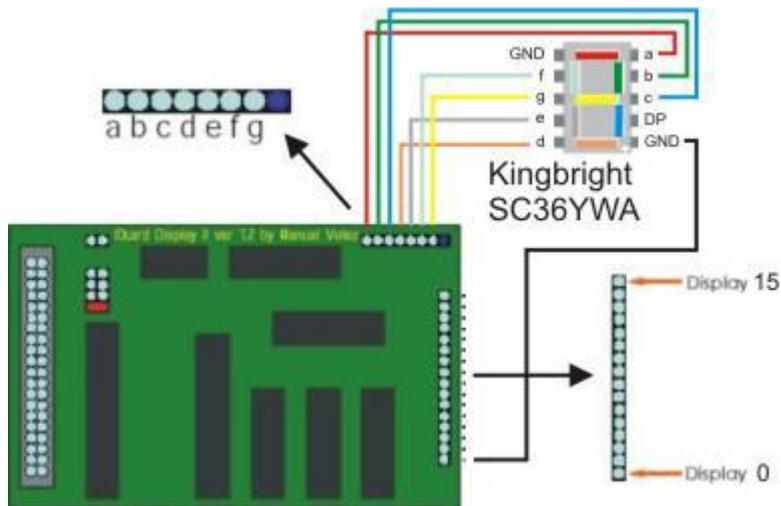
Cut with a hacksaw.

Note that these encoders available from Opencockpits incorporate a pushbutton switch. The 3 top legs are for the encoder (known as "A", "C" & "B" legs) and the 2 bottom legs are for the pushbutton. The outer "A" & "B" legs of the encoder connect to two **consecutive** inputs of the Mastercard and the centre "C" leg connects to the corresponding Ground.

For my radio two encoders provide high and low digit selection. You may choose to use the more authentic dual concentric encoder or a single encoder with the encoder's pushbutton alternating between High & Low selection.

NOTE: Pushbutton selection of high and low selection is done within the code of SIOC. Search the Opencockpits forum for example code to achieve this.





Now onto the heart of the system, the displays board. The Opencockpits display board controls up to 16 x 7-segment displays connected as shown in this diagram. The displays PCB caters for all the associated connections to the card via multipin cables that you will need to make.

More on that later.

As you can see from the picture above, the 7-segments of each display PCB connects to the board via a 7pin connector and you may have to connect several 7 pin connectors to one board. Some use splitter cables but I decided to take a pcb approach and solder a multipin board to the card using strip veroboard.

The Common Cathodes connect to the pins numbered 0 – 15.

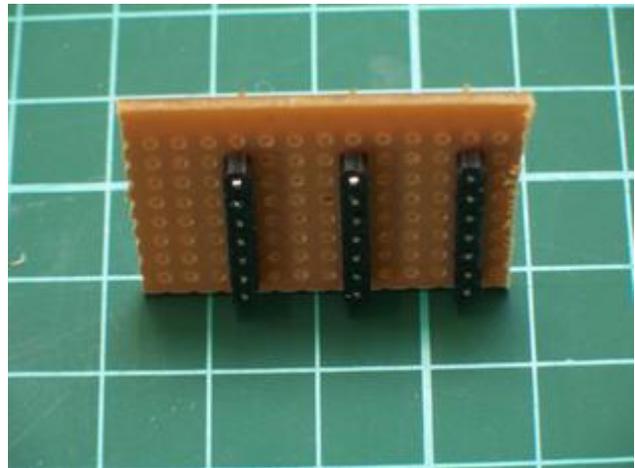


Only takes a few minutes and provides easier multipin connection.



Standard pcb pins were used but due to the need to push them through from the underside I modified them by pushing the plastic support down to the base of the pins.

Here you can see the rows of pins inserted from the underside of the veroboard.



Now onto the construction of the 7-segment displays. Again always use the mounting PCB's. They only cost a few dollars each and make it a breeze to install.

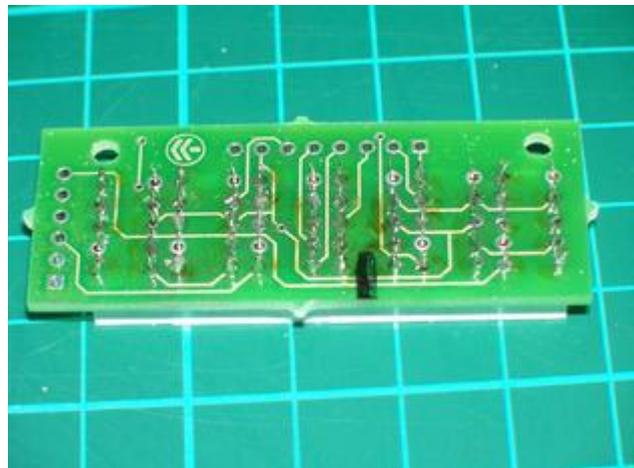




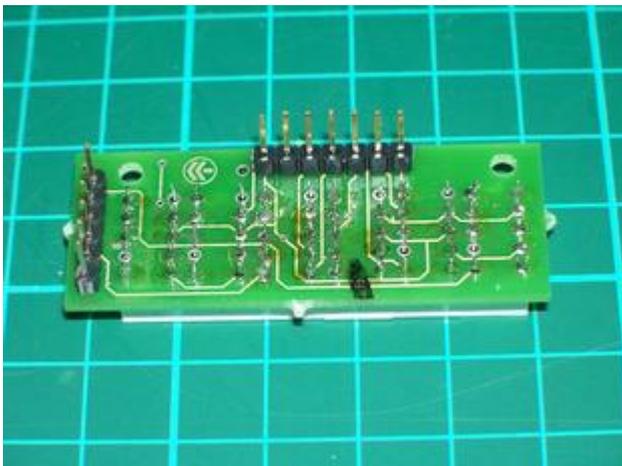
Place the displays onto the PCB's then mount the backplate over the displays prior to soldering. Turn the whole lot over and solder the displays onto the PCB's while mounted in the backplate. This will allow the displays to more easily insert through the backplate later on during final assembly. These backplates are laser cut to very fine tolerance and if you solder without doing this you'll end up needing to file the backplate holes to fit the displays. (This photo shows the comm panel but the principle is the same).

This is the rear of the 6 digit display card. The black mark indicates which display has the decimal point.

Make sure you place the 7-segs onto the front of the PCB and solder to the rear. The front is indicated by the Opencockpits logo and writing.



NOTE: You will only need to solder pins 2(f), 3(g), 4(e), 5(d), 6(GND), 8(c), 9(b), 10(a). Pin 7 is the decimal point and will need a separate wire connecting to a Mastercard output. Pin 1 can be left unsoldered as it's just another Ground pin.



Solder connection pins onto the rear of the PCB to provide multipin connectors. The top row of 7 pins are for the 7 segments of each display (a,b,c,d,e,f,g,GND) and the 6 pins to the left are for the common cathode of each display. In this case there are 6. The 5 display PCB will have 5 pins and the 3 display PCB has 3. Clever hey!

Secure your completed displays PCB's onto your panel with hot glue at each corner.



HOT TIP! To connect the Decimal Point (pin #7) wire it to a spare output of the Mastercard but don't connect a GND cable from the display to the output card. The output will utilize the display card GND and therefore its own buffering and you won't need a resistor in circuit. The DP will also be the same brightness as the other digits. I connected both stby & act DP to a single Mastercard output.

NOTE: Some builders advocate hard wiring the first digit (#1) to a Mastercard output as it never changes, however Nico Kaan recommends wiring as a fully operational digit driven from the display card. This has the advantage of complete control over the digit via SIOC therefore allowing display dimming and full display testing by writing "8" to the display when pressing the Test switch. This approach does consume one extra display card output per frequency; however it also offers greater flexibility. It also simplifies soldering and you don't have to cut the circuit tracks in order to isolate the first digit which you need to do if you hard wire it.

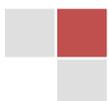


Your next major work is making up cables to connect your displays to your boards. I highly recommend making up multipin connectors. Don't try soldering directly to the display pins. Whatever method you end up using you will have a lot of pin connections to make, it's unavoidable!!

As you can see the 7-segment cables can be paralleled together but the Cathode connections need separate cables to connect to their respective pins on the display board. One NAV radio consists of 10 digits so you'll need one

display board. **See Appendix 1 for the circuit diagram of my complete pedestal.**

NOTE: If you intend building multiple units as I did you will need to decide which displays connect to which board, remembering there is a maximum of 16 displays per board. This will dictate how many cables you'll need and how many 7-segment cables can be paralleled together. The cable lengths will also be dependent upon where your display boards are located in relation to the radio, but I would strongly advise making them longer than expected to allow for ease of access. If you end up building a complete pedestal setup you'll have a lot of cables to contend with.





The digital displays look more aesthetically appealing with a coloured lens over them. I used standard red cellophane sandwiched between the front and back plates and it works well.

The only criticism I have is that it's a little flimsy and prone to tearing but if you take care it is very cheap and easy and quite effective.



Cut two strips about 50mm x 100mm.

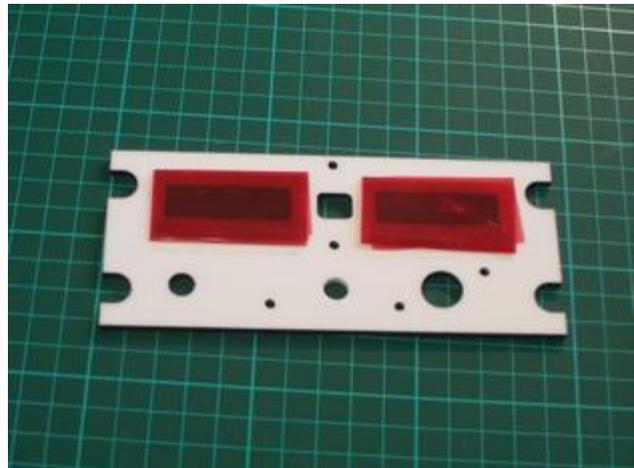
And fold into 3.



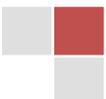


Use very thin double sided tape to stick the cellophane in place. You should be able to get this tape at office stationary stores. Don't use the foam style double sided mounting tape, it's far too thick.

And here is the result. One advantage of cellophane is that it is very thin and doesn't provide too much bulk between the front and back plates.



Here's an example of the final wiring mess for the full set of radios in the pedestal. It's really important therefore to take care making up cables to the length required and keeping good records of connections.



BACKLIGHTING

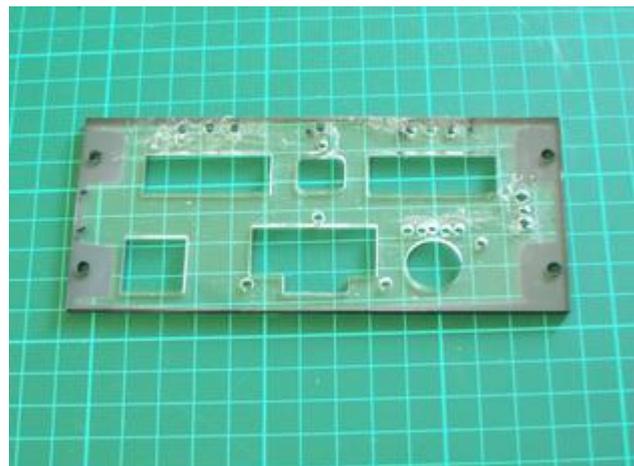
You may already have a preference for backlighting but I found after my own research and testing that I preferred the whiter glow and lower current draw of LED's. I used 3mm White LED's with a brightness of 15000mcd purchased on ebay from China. These are VERY bright and I could easily have gone for a lower brightness, therefore I would recommend something around 10000mcd. You can even go for the warm white variety if you prefer the warmer look similar to incandescent globes. There's nothing fancy about this method and therefore it can be applied simply and cheaply by anyone with the most meagre of skills.



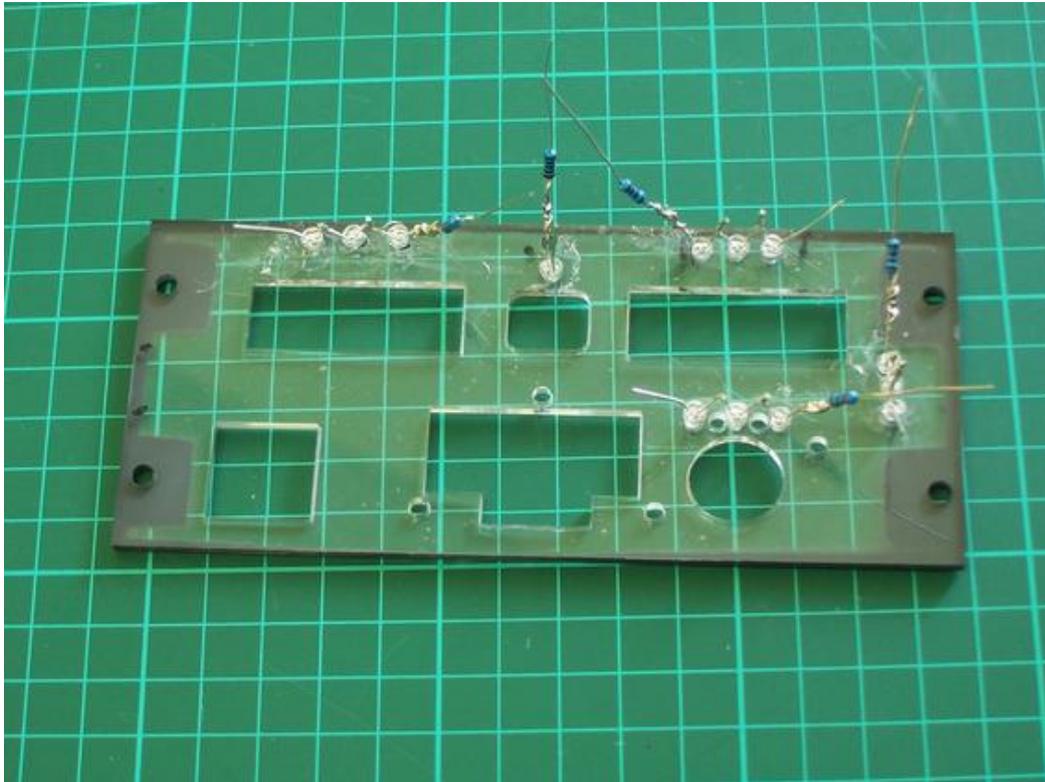
I'm driving my backlighting from a 12v DC power supply and connecting them in a series configuration. The maximum number of these LED's that can be driven from 12v in series is 3, so most of my LED's are grouped this way along with a resistor. These LED's have a working voltage of 3.4v and current draw of 20mA which results in a resistor requirement of 100 ohms per 3 LED's.

NOTE: Take a look at <http://led.linear1.org/led.wiz> for a very useful LED array resistor calculator. Also be sure to connect the LED's with the correct polarity i.e. -ve leg of one LED to the +ve leg of the next and so on. The resistor can be connected to either the -ve or +ve end of the array but for convention stick with one end throughout your arrays. I connected my resistors to the -ve end of all arrays.

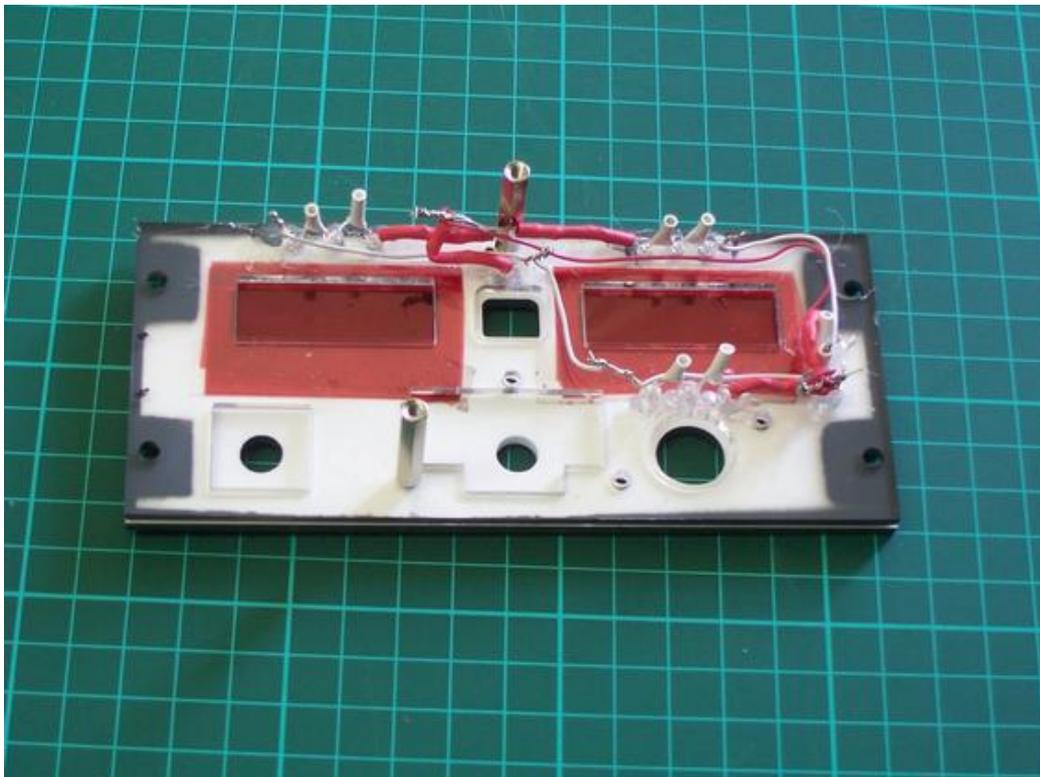
Drill 3mm holes in the backplate to mount the LED's. Use the front plate as a guide to mark the position of the holes depending on where the writing is that you want to backlight.



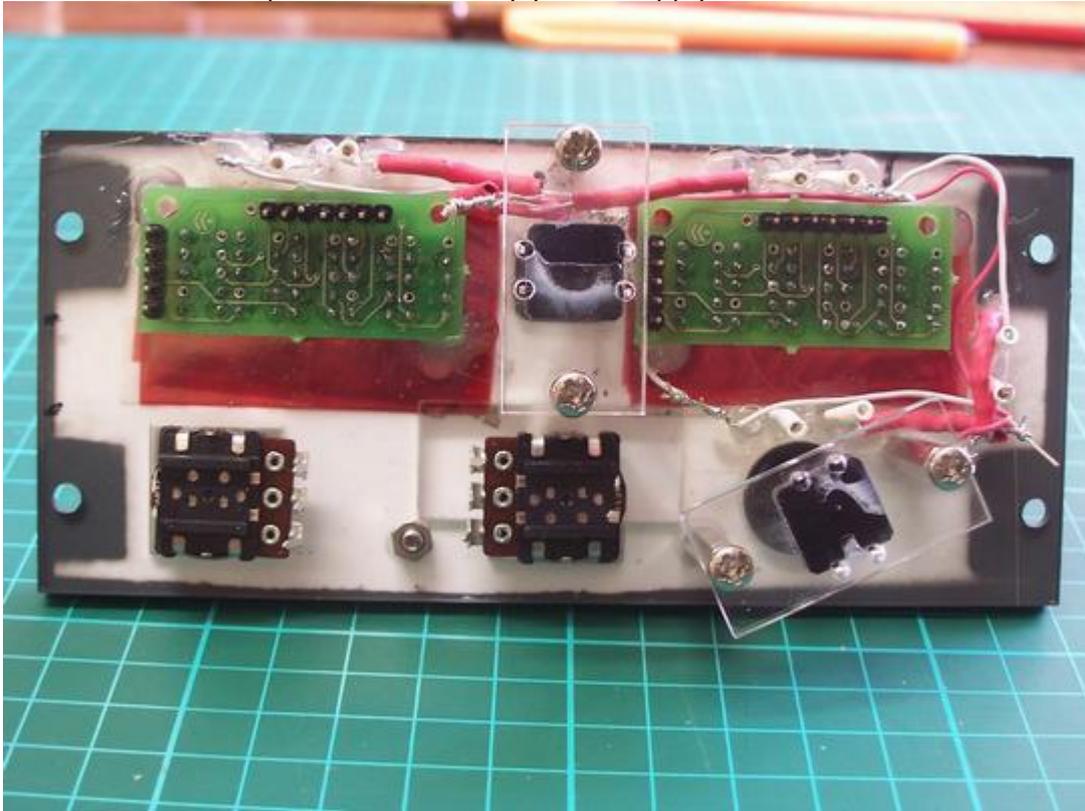
Place the LED's in the holes and adjust for correct placement then use hot glue to hold them in place. Try to group -ve and +ve ends in close proximity as it will be easier to connect them together later.



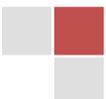
Use heatshrink to protect resistor legs and other wires that you don't want contacting.



Now join all -ve ends of each LED group together and all +ve ends. Your 12v supply connects to the respective -ve & +ve legs of the completed circuit. I used a piece of strip veroboard and PCB pins to connect my power supply to.



And here is the result. Not bad hey?



This process of backlighting should take approximately 1 hour per panel from start to finish.

The final process of getting the radio working is programming the operations in SIOC. I'm not going into detail here about this process but I would point you to Nico Kaan's website at <http://www.lekseecon.nl/sioc.html> for an explanation of this very powerful software. You can also download examples of code to adapt and use for your radio.

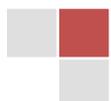
Weblinks List:

- <http://www.opencockpits.com/catalog/index.php>
- <http://www.opencockpits.com/>
- <http://personales.ya.com/micabina737/indexi.htm>.
- <http://www.lekseecon.nl/>
- <http://led.linear1.org/led.wiz>

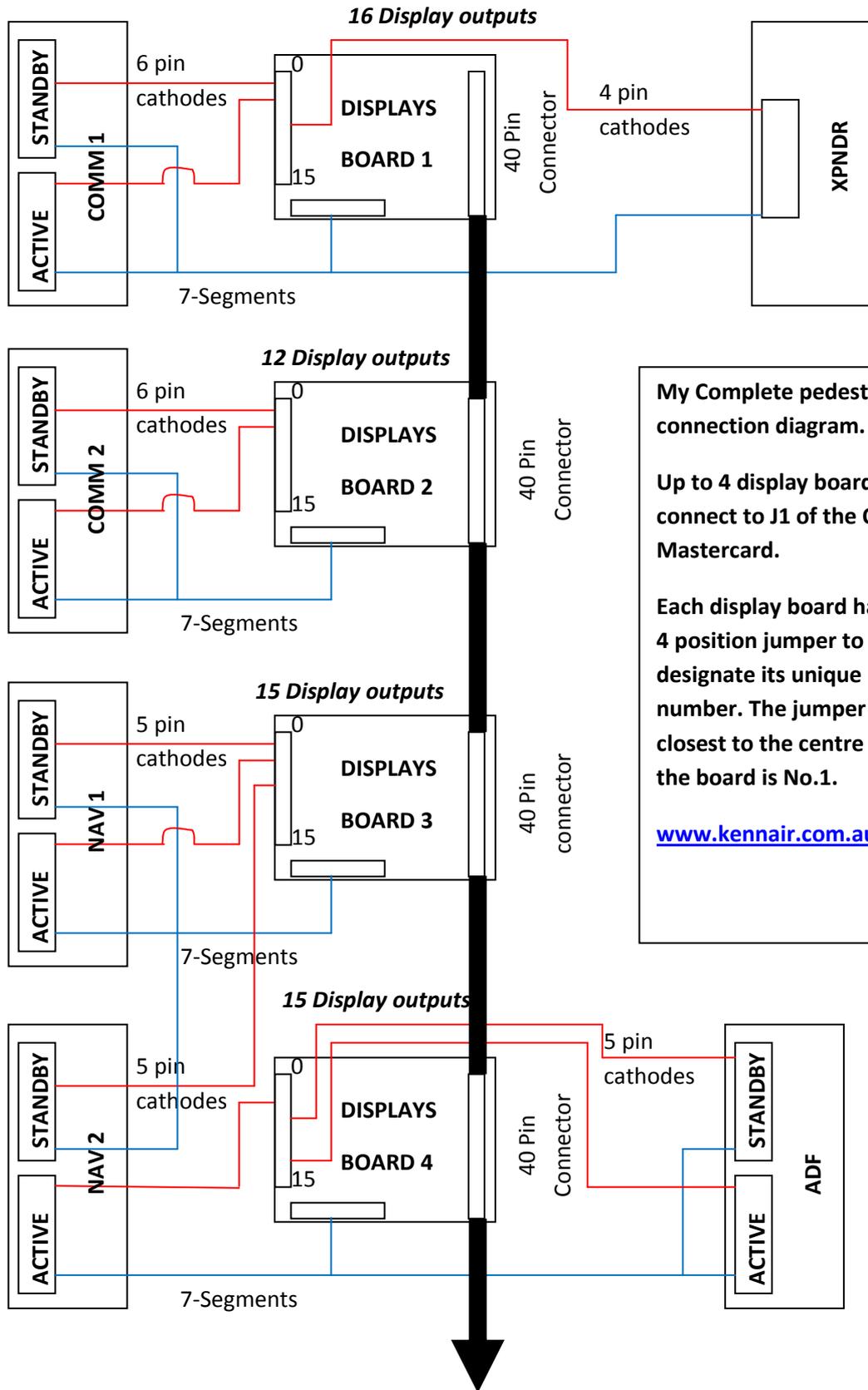
For more detailed photos used in this guide, go to my website at <http://www.kennair.com.au/avionics.html>.

Ken Brand.

DISCLAIMER: Please use the instructions in this tutorial at your own risk. The author claims no responsibility for hardware or electrical damage as a result. This tutorial is made available as a guide only and represents the process, views and opinions of the author and not of Opencockpits or any affiliates.



Appendix 1.



My Complete pedestal connection diagram.

Up to 4 display boards connect to J1 of the OC Mastercard.

Each display board has a 4 position jumper to designate its unique number. The jumper closest to the centre of the board is No.1.

www.kennair.com.au



40 Pin Connector to J1 of Opencockpits Mastercard

Appendix 2.

This is a nav1 & 2 file courtesy of Nico Kaan (<http://www.leksecon.nl/>) and works well with this nav radio build. Copy this text into a Notepad file, change the input/output and display digit numbering to comply with your hardware and import into SIOC. Delete the NAV2 section if not required

```
// *****
// * Config_SIOC ver 1.98 - By Manolo Vélez - www.opencockpits.com
// *****
// * FileName : Nav1_2.txt
// * Author Nico Kaan
// * Date : 10/11/2007
// * modified by Nico Kaan, April 18th, 2008
// * Also incorporates a display test function

//*****
//**** NAV 1 *****
//*****

Var 1100 name Nav1_Act

Var 1102 name FS_N1_SB_BCD Link FSUIPC_INOUT Offset $311E Length 2 // FS Nav1 standby frequency in BCD format
Var 1103 name FS_N1_ACT_BCD Link FSUIPC_INOUT Offset $0350 Length 2 // FS Nav1 active frequency in BCD format
{
&Nav1_Act = FROMBCD &FS_N1_ACT_BCD
Call &OutNav1_Act
CALL &N1_LH_ROT_VAL // Align rotary with new N1 SB integer val
CALL &N1_RH_ROT_VAL // Align rotary with new N1 SB decimal val
CALL &N1_UPDATE_LHS
CALL &N1_UPDATE_RHS
Call &OutNav1_SB
}

Var 1104 name FS_N1_SWAP Link FSUIPC_OUT Offset $3123 Length 1 // FS Nav1 active standby swap

Var 1105 name N1_SB_AS_DEC // Nav1 standby frequency in decimal format
Var 1106 name N1_SB_LHS // Nav1 standby frequency integers
Var 1107 name N1_SB_RHS // Nav1 standby frequency decimals
Var 1108 name N1_RHS_ROT_VAL // Nav1 right hand rotary encoder ref value
Var 1109 name N1_LHS_ROT_VAL // Nav1 left hand rotary encoder ref value

Var 1110 name ROT_N1_LHS Link IOCARD_ENCODER Input 13 Aceleration 1 Type 2
{
L0 = &ROT_N1_LHS
&N1_LHS_ROT_VAL = ROTATE 8 17 L0
CALL &N1_UPDATE_LHS
CALL &SET_FS_N1_SB
CALL &OutNav1_SB
}

Var 1111 name ROT_N1_RHS Link IOCARD_ENCODER Input 15 Aceleration 1 Type 2
{
L0 = &ROT_N1_RHS * -1
&N1_RHS_ROT_VAL = ROTATE 0 19 L0
CALL &N1_UPDATE_RHS
CALL &SET_FS_N1_SB
CALL &OutNav1_SB
}

Var 1112 name SW_N1_SWAP Link IOCARD_SW Input 17 Type 1
{
&FS_N1_SWAP = TOGGLE 1
}

Var 1115 name SW_N1_TEST Link IOCARD_SW Input 19 // NAV TEST button sends 8's to Displays
{
```



```

IF &SW_N1_TEST = 1
{
  &DISP_N1_ACT = 88888
  &DISP_N1_SB = 88888
}
ELSE
{
  CALL &OutNAV1_Act
  CALL &OutNAV1_SB
}
}

```

```

Var 1120 name DISP_N1_SB Link IOCARD_DISPLAY Digit 32 Numbers 5
Var 1121 name DISP_N1_ACT Link IOCARD_DISPLAY Digit 37 Numbers 5
Var 1122 name N1_DP Link IOCARD_OUT Output 11 // Decimal Point

```

```

Var 1130 name N1_LH_ROT_VAL Link SUBROUTINE // Aligns LH rotary ref with Nav1 SB freq
{
  L0 = FROMBCD &FS_N1_SB_BCD
  L1 = L0 / 100
  &N1_LHS_ROT_VAL = TRUNC L1
}

```

```

Var 1131 name N1_RH_ROT_VAL Link SUBROUTINE // Aligns RH rotary ref with Nav1 SB freq
{
  L0 = FROMBCD &FS_N1_SB_BCD
  L1 = &N1_LHS_ROT_VAL * 100
  L2 = L0 - L1
  &N1_RHS_ROT_VAL = L2 / 5
}

```

```

Var 1132 name N1_UPDATE_LHS Link SUBROUTINE // Update Nav1 stanby integers
{
  &N1_SB_LHS = &N1_LHS_ROT_VAL
}

```

```

Var 1133 name N1_UPDATE_RHS Link SUBROUTINE // Update Nav1 standby decimals
{
  L0 = &N1_RHS_ROT_VAL * 5
  &N1_SB_RHS = TRUNC L0
}

```

```

Var 1134 name SET_FS_N1_SB Link SUBROUTINE // Update Nav1 standby frequency in FS
{
  L0 = &N1_SB_LHS * 100
  L1 = L0 + &N1_SB_RHS
  &FS_N1_SB_BCD = TOBCD L1
}

```

```

Var 1140 name OutNAV1_Act Link SUBROUTINE
{
  //IF &MAST_SW = 1
  //{
  L0 = &Nav1_act
  &DISP_N1_ACT = L0 + 10000
  }
  //ELSE
  //{
  &DISP_N1_ACT = -999999 // blank
  //}
  //}
}

```

```

Var 1141 name OutNAV1_SB Link SUBROUTINE
{
  //IF &MAST_SW = 1
  //{
  &N1_DP = 1
  L0 = &N1_SB_LHS * 100
  L1 = L0 + &N1_SB_RHS
  &DISP_N1_SB = L1 + 10000
}
}

```



```

}
//ELSE
//{
//&N1_DP = 0
//&DISP_N1_SB = -999999 // blank
//}
//}

//*****
//**** NAV 2 ****
//*****

Var 1150 name Nav2_Act

Var 1152 name FS_N2_SB_BCD Link FSUIPC_INOUT Offset $311E Length 2 // FS Nav2 standby frequency in BCD format
Var 1153 name FS_N2_ACT_BCD Link FSUIPC_INOUT Offset $3120 Length 2 // FS Nav2 active frequency in BCD format
{
&Nav2_Act = FROMBCD &FS_N2_ACT_BCD
Call &OutNav2_Act
CALL &N2_LH_ROT_VAL // Align rotary with new N2 SB integer val
CALL &N2_RH_ROT_VAL // Align rotary with new N2 SB decimal val
CALL &N2_UPDATE_LHS
CALL &N2_UPDATE_RHS
Call &OutNav2_SB
}

Var 1154 name FS_N2_SWAP Link FSUIPC_OUT Offset $3123 Length 1 // FS Nav2 active standby swap

Var 1155 name N2_SB_AS_DEC // Nav2 standby frequency in decimal format
Var 1156 name N2_SB_LHS // Nav2 standby frequency integers
Var 1157 name N2_SB_RHS // Nav2 standby frequency decimals
Var 1158 name N2_RHS_ROT_VAL // Nav2 right hand rotary encoder ref value
Var 1159 name N2_LHS_ROT_VAL // Nav2 left hand rotary encoder ref value

Var 1160 name ROT_N2_LHS Link IOCARD_ENCODER Input 11 Aceleration 1 Type 2
{
L0 = &ROT_N2_LHS * -1
&N2_LHS_ROT_VAL = ROTATE 8 17 L0
CALL &N2_UPDATE_LHS
CALL &SET_FS_N2_SB
CALL &OutNav2_SB
}

Var 1161 name ROT_N2_RHS Link IOCARD_ENCODER Input 9 Aceleration 1 Type 2
{
L0 = &ROT_N2_RHS
&N2_RHS_ROT_VAL = ROTATE 0 19 L0
CALL &N2_UPDATE_RHS
CALL &SET_FS_N2_SB
CALL &OutNav2_SB
}

Var 1162 name SW_N2_SWAP Link IOCARD_SW Input 8 Type 1
{
&FS_N2_SWAP = TOGGLE 0
}

Var 1165 name SW_N2_TEST Link IOCARD_SW Input 20 // NAV TEST button sends 8's to Displays
{
IF &SW_N2_TEST = 1
{
&DISP_N2_ACT = 88888
&DISP_N2_SB = 88888
}
ELSE
{
CALL &OutNAV2_Act
CALL &OutNAV2_SB
}
}
}

```



```

Var 1170 name DISP_N2_SB Link IOCARD_DISPLAY Digit 42 Numbers 5
Var 1171 name DISP_N2_ACT Link IOCARD_DISPLAY Digit 58 Numbers 5
Var 1172 name N2_DP Link IOCARD_OUT Output 13 // Decimal Point

```

```

Var 1180 name N2_LH_ROT_VAL Link SUBROUTINE // Aligns LH rotary ref with Nav2 SB freq
{
L0 = FROMBCD &FS_N2_SB_BCD
L1 = L0 / 100
&N2_LHS_ROT_VAL = TRUNC L1
}

```

```

Var 1181 name N2_RH_ROT_VAL Link SUBROUTINE // Aligns RH rotary ref with Nav2 SB freq
{
L0 = FROMBCD &FS_N2_SB_BCD
L1 = &N2_LHS_ROT_VAL * 100
L2 = L0 - L1
&N2_RHS_ROT_VAL = L2 / 5
}

```

```

Var 1182 name N2_UPDATE_LHS Link SUBROUTINE // Update Nav2 standby integers
{
&N2_SB_LHS = &N2_LHS_ROT_VAL
}

```

```

Var 1183 name N2_UPDATE_RHS Link SUBROUTINE // Update Nav2 standby decimals
{
L0 = &N2_RHS_ROT_VAL * 5
&N2_SB_RHS = TRUNC L0
}

```

```

Var 1184 name SET_FS_N2_SB Link SUBROUTINE // Update Nav2 standby frequency in FS
{
L0 = &N2_SB_LHS * 100
L1 = L0 + &N2_SB_RHS
&FS_N2_SB_BCD = TOBCD L1
}

```

```

Var 1190 name OutNAV2_Act Link SUBROUTINE
{
//IF &MAST_SW = 1
//{
L0 = &Nav2_act
&DISP_N2_ACT = L0 + 10000
}
//ELSE
//{
//&DISP_N2_ACT = -999999 // blank
//}
//}

```

```

Var 1191 name OutNAV2_SB Link SUBROUTINE
{
//IF &MAST_SW = 1
//{
&N2_DP = 1
L0 = &N2_SB_LHS * 100
L1 = L0 + &N2_SB_RHS
&DISP_N2_SB = L1 + 10000
}
//ELSE
//{
//&N2_DP = 0
//&DISP_N2_SB = -999999 // blank
//}
//}

```

